

234(6): Calculation of the Acceleration for Any Metric.

As in previous notes the acceleration of an orbit can be written in general as:

$$\underline{a} = \left(\frac{d^2 r}{d\tau^2} - r \left(\frac{d\theta}{d\tau} \right)^2 \right) \underline{e}_r + \left(r \frac{d^2 \theta}{d\tau^2} + 2 \left(\frac{dr}{d\tau} \right) \left(\frac{d\theta}{d\tau} \right) \right) \underline{e}_\theta \quad (1)$$

For a metric of type:

$$ds^2 = c^2 d\tau^2 = A c^2 dt^2 - B dr^2 - r^2 d\theta^2 \quad (2)$$

The angular momentum is a constant of motion:

$$L = m r^2 \frac{d\theta}{d\tau} \quad (3)$$

and:
$$r \frac{d^2 \theta}{d\tau^2} + 2 \left(\frac{dr}{d\tau} \right) \left(\frac{d\theta}{d\tau} \right) = 0 \quad (4)$$

so:
$$\underline{a} = \left(\frac{d^2 r}{d\tau^2} - \frac{L^2}{m^2 r^3} \right) \underline{e}_r \quad (5)$$

Any metric of type (2) produces the acceleration (5).

This can be rewritten as:

$$\underline{a} = \left(\frac{L}{mr} \right)^2 \left(\left(\frac{dr}{d\theta} \right) \frac{d}{dr} \left(\frac{1}{r^2} \frac{dr}{d\theta} \right) - \frac{1}{r} \right) \underline{e}_r \quad (6)$$

which is a generalization of Newtonian theory and a valid new cosmology based on the Minkowski metric, or any metric of type (2). For the Minkowski metric:

$$\left(\frac{dr}{d\theta} \right)^2 = r^4 \left(\left(\frac{1}{L} \right)^2 - \frac{1}{r^2} \right) \quad (7)$$

where

$$p = \gamma m v, \quad \text{--- (8)}$$

$$\underline{L} = \gamma m r^2 \underline{\omega} \quad \text{--- (9)}$$

are the linear and angular momenta. Therefore the acceleration in this case is found from a combination of eqs (6) and (7). The orbit is therefore characterized by the acceleration (6) and by:

$$\left(\frac{p}{L}\right)^2 = \frac{1}{r^2} \left(1 + \frac{1}{r^2} \left(\frac{dr}{d\theta}\right)^2\right) \quad \text{--- (10)}$$

For an elliptical orbit:

$$\frac{dr}{d\theta} = \frac{Er^2}{d} \sin\theta \quad \text{--- (11)}$$

so

$$\left(\frac{p}{L}\right)^2 = \frac{1}{r^2} \left(1 + \left(\frac{E}{d}\right)^2 r^2 \sin^2\theta\right) \quad \text{--- (12)}$$

i.e

$$\left(\frac{pr}{L}\right)^2 = 1 + \left(\frac{Er \sin\theta}{d}\right)^2 \quad \text{--- (13)}$$

and for a circular orbit:

$$\left. \begin{aligned} L &= pr, \\ E &= 0. \end{aligned} \right\} \quad \text{--- (14)}$$

The acceleration for an elliptical orbit is given by:

$$\underline{a} = \left(\frac{L}{mr}\right)^2 \left(\left(\frac{dr}{d\theta}\right) \frac{d}{dr} \sin\theta - \frac{1}{r} \right) \underline{e}_r \quad \text{--- (15)}$$

$$\begin{aligned}
 &= \left(\frac{L}{mr} \right)^2 \left(\frac{\epsilon r^2}{d} \sin \theta \frac{d \sin \theta}{dr} - \frac{1}{r} \right) \frac{e}{r} \\
 &= \left(\frac{L^2 \epsilon \cos \theta}{m^2 d r^2} - \frac{L^2}{m^2 r^3} \right) \frac{e}{r} \\
 \underline{a} &= - \frac{L^2}{m^2 r^2 d} \frac{e}{r} \quad - (16)
 \end{aligned}$$

as in the previous note. The precise result is:

$$\underline{a} = \left(\frac{L^2}{m^2 r^3} - \frac{L^2}{m^2 r^2 d} - \frac{L^2}{m^2 r^3} \right) \frac{e}{r}, \quad - (17)$$

$$\left(\frac{r}{L} \right)^2 = \frac{1}{r^2} \left(1 + \left(\frac{\epsilon r}{d} \right)^2 \sin^2 \theta \right), \quad - (18)$$

where

$$\cos \theta = \frac{1}{\epsilon} \left(\frac{d}{r} - 1 \right) \quad - (19)$$

so

$$\left(\frac{r}{L} \right)^2 = 1 + \frac{1}{d^2} \left(\epsilon^2 r^2 - (d-r)^2 \right) \quad - (20)$$

For the orbits and metrics the result is different. In this theory:

$$L = \gamma m r^2 \omega \quad - (21)$$

so

$$\underline{a} = - \frac{\gamma^2 r^2 \omega^2}{d} \frac{e}{r} \quad - (22)$$

7) i.e.

$$\underline{a} = - \left(1 - \frac{v^2}{c^2} \right)^{-1} \frac{r^2 \omega^2}{d} \underline{e}_r \quad - (23)$$

$$\underline{a} = - \frac{1}{d} \frac{(\omega r)^2}{\left(1 - \frac{v^2}{c^2} \right)} \underline{e}_r \quad - (24)$$

In the limit:

$$v \ll c \quad - (25)$$

and for a circular orbit:

$$d = r \quad - (26)$$

then

$$\boxed{\underline{a} = - \omega^2 r \underline{e}_r} \quad - (27)$$

which is the centripetal acceleration due to the elliptical orbit. The orbit is caused by the metric itself, i.e. by a rotating frame of reference.
